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On a class of locally dually flat Finsler metrics with isotropic S-curvature

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Abstract

Dually flat Finsler metrics form a special and valuable class of Finsler metrics in Finsler information geometry, which play a very important role in studying flat Finsler information structure. In this paper, we prove that every locally dually flat generalized Randers metric with isotropic S-curvature is locally Minkowskian.

Keywords: Locally dually flat metric; S-curvature

1. Introduction

In [1], Amari-Nagaoka introduced the notion of dually flat Riemannian metrics when they studied information geometry on Riemannian the manifolds. Information geometry has emerged from investigating the geometrical structure of a family of probability distributions and has been applied successfully to various areas including statistical inference, control system theory and multi-terminal information theory. In Finsler geometry, Shen extends the notion of locally du ally flatness for Finsler metrics [2]. Dually flat Finsler metrics form a special and valuable class of Finsler metrics in Finsler information geometry, which play a very important role in studying flat Finsler information structure [3-6].

A Finsler metric F = F(x, y) on a manifold M is said to be locally dually flat if at any point there is a standard coordinate system (x^i, y^i) in TM which satisfies

$$(F^2)_{x^k y^l} y^k = 2(F^2)_{x^l}.$$

In this case, the coordinate (x^i) is called an adapted local coordinate system. It is easy to see that every locally Minkowskian metric is locally dually flat. But the converse is not true, generally [3].

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The S-curvature is constructed by Shen for given comparison theorems on Finsler manifolds [7]. A

A Finsler metric F on an n-dimensional manifold M is said to have isotropic S-curvature if isotopic S = (n+1)c(x)F, for some scalar function c on M. It is known that some of Randers metrics are of S-curvature [8, 9]. This is one of our motivations for considering Finsler metrics of isotropic S-curvature.

In this paper, we show that a locally dually flat generalized Randers metric with isotropic Scurvature reduces to a locally Minkowskian metric. More precisely, we prove the following.

Theorem 1.1. Let $F^2 = c_1 \alpha^2 + 2c_2 \alpha \beta + c_1 \beta^2$ $(c_1 \neq 0, c_2 \neq 0)$ be a non-Randers type and non-Riemannian generalized Randers metric on a manifold M of dimension $n \ge 3$. Then F is locally dually flat with isotropic Scurvature, S = (n+1)c(x)F, if and only if it is locally Minlowskian.

2. Preliminaries

A Finsler metric on an n-dimensional manifold M is a function $F:TM \rightarrow [0,\infty)$ which has the following properties: (i) F is C^{∞} on $TM_0 := TM \setminus \{0\}$; (ii) F is positively 1-homogeneous on the fibers of tangent bundle TM; (iii) for each $y \in T_x M$ the following quadratic form g_y on $T_x M$ is positive definite,

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$$g_{y}(u,v) \coloneqq \frac{1}{2} \frac{\partial^{2}}{\partial s \partial t} [F^{2}(y + su + tv)]|_{s,t=0, u,v \in T_{x}} M$$

Given a Finsler manifold (M, F), a global vector field G is induced by F on TM_0 which in a standard coordinate (x_i, y_i) for TM_0 is given by $G = y^i \frac{\partial}{\partial x^i} - 2G^i(x, y) \frac{\partial}{\partial y^i}$, where G^i are

the coefficients of the spray associated with F and given by the following

$$G^{i} = \frac{g^{il}}{4} \left\{ \left[F^{2} \right]_{x^{k} y^{l}} y^{k} - \left[F^{2} \right]_{x^{l}} \right\}$$

Indeed, G is called the associated spray to (M, F) [10].

A Finsler metric F(x, y) on an open domain $U \subset \mathbb{R}^n$ is said to be locally projectively flat if its geodesic coefficients G^i are in the form $G^i(x, y) = P(x, y)y^i$, where $P: TU = U \times \mathbb{R}^n \to \mathbb{R}$ is positively homogeneous with degree one, $P(x, \lambda y) = \lambda P(x, y), \lambda > 0$. We call P(x, y) the projective factor of F.

A Finsler metric F = F(x, y) on a manifold M is said to be locally dually flat if at any point there is a standard coordinate system (x^i, y^i) in TM such that $L = F^2(x, y)$ satisfies

$$L_{x^{k}y^{l}}y^{k} = 2L_{x^{l}}.$$
 (1)

In this case, the coordinate (x^i) is called an adapted local coordinate system. It is easy to see that every locally Minkowskian metric is satisfied in the above equation, hence it is locally dually flat. In [3], the following is proved.

Lemma 2.1. ([3]) Let F = F(x, y) be a Finsler metric on an open subset $U \subset \mathbb{R}^n$. Then F is locally flat and projectively flat on U if and only if $F_{x^k} = CFF_{y^k}$, where C is a constant.

For a Finsler metric F on an n-dimensional manifold M, the Busemann- Hausdorff volume form $dV_F = \sigma_F(x)dx^1...dx^n$ is defined by

$$\sigma(F) \coloneqq \frac{Vol(B^{n}(1))}{Vol\left\{(y^{i}) \in R^{n} | F(y^{i} \frac{\partial}{\partial x^{i}}|_{x})\right\}}$$

Here Vol denotes the Euclidean volume and $B^{n}(1)$ denotes the unit ball in R^{n} .

Then the S-curvature is defined by

$$S(y) \coloneqq \frac{\partial G^{i}}{\partial y^{i}}(x, y) - y^{i} \frac{\partial}{\partial x^{i}} [\ln \sigma_{F}(x)]$$

where $y = y^{i} \frac{\partial}{\partial x^{i}}|_{x} \in T_{x}M$ [7]. **S** said to be
isotropic if there is a scalar function $c(x)$ on M
such that

$$S(x, y) = (n+1)c(x)F(x, y)$$

3. Proof of Theorem 1.1.

In this section, we are going to prove the Theorem 1.1. First let us introduce our notations. Define $b_{i|i}$ by

$$b_{i|j}\theta^j \coloneqq db_i - b_j\theta_i^j$$

where $\theta^i := dx^i$ and $\theta^j_i := \Gamma^j_{ik} dx^k$ denote the Levi-Civita connection form of α . Put

$$r_{ij} := \frac{1}{2} (b_{i|j} + b_{j|i}), \ s_{ij} := \frac{1}{2} (b_{i|j} - b_{j|i})$$

Clearly, β is closed if and only if $s_{ij} = 0$ [11]. Put

$$r_{00} \coloneqq r_{ij} y^{i} y^{j}, \ s_{k0} \coloneqq s_{km} y^{m}, \ r_{j} \coloneqq b^{i} r_{ij},$$
$$s_{j} \coloneqq b^{i} s_{ij}$$

Let $r_{i0} \coloneqq r_{ij} y^{j}$, $s_{i0} \coloneqq s_{ij} y^{j}$ and $s_{0} \coloneqq s_{j} y^{j}$. We have the following identities

$$\alpha_{x^{k}} = \frac{y_{m}}{\alpha} \frac{\partial G_{\alpha}^{m}}{\partial y^{k}}, \quad \beta_{x^{k}} = b_{m|k} y^{m} + b_{m} \frac{\partial G_{\alpha}^{m}}{\partial y^{k}},$$
$$s_{y^{k}} = \frac{\alpha b_{k} - s y_{k}}{\alpha^{2}} \tag{2}$$

where $s := \frac{\beta}{\alpha}$ and $y_k := a_{jk} y^j$. Let $F^2 = c_1 \alpha^2 + 2c_2 \alpha \beta + c_3 \beta^2$ be a generalized Randers metric on an open subset $U \subset \mathbb{R}^n$, where c_i 's (i = 1, 2) are non-zero constants [12-14]. To prove the Theorem 1.1, we need the following.

Theorem 3.1. ([5]) Let $F = \alpha \phi(s)$, $s = \frac{\beta}{\alpha}$ be an (α, β) -metric on an n- dimensional manifold M^n $(n \ge 3)$, where $\alpha = \sqrt{a_{ij} y^i y^j}$ is a Riemannian metric and $\beta = b_i(x) y^i \ne 0$ is a 1-form on M. Suppose that F is not Riemannian and $\phi'(s) \ne 0$. Then F is locally dually flat on M if and only if α, β and $\phi = \phi(s)$ satisfy

$$\begin{split} s_{l0} &= \frac{1}{3} (\beta \theta_l - \theta b_l), \\ r_{00} &= \frac{2}{3} \theta \beta + \left[\tau + \frac{2}{3} (b^2 \tau - \theta_l b^l) \right] \alpha^2 + \frac{1}{3} (3k_2 - 2 - 3k_3 b^2) \tau \beta^2, \\ G_{\alpha}^{\ l} &= \frac{1}{3} \left[2\theta + (3k_1 - 2) \tau \beta \right] y^l + \frac{1}{3} (\theta^l - \tau b^l) \alpha^2 + \frac{1}{2} k_3 \tau \beta^2 b^l, \\ \tau \left[s \left(k_2 - k_3 s^2 \right) (\phi \phi^{\prime} - s \phi^{\prime 2} - s \phi \phi^{\prime \prime}) - (\phi^{\prime 2} + \phi \phi^{\prime \prime}) + k_1 \phi (\phi - s \phi^{\prime \prime}) \right] = 0, \end{split}$$

where $\tau = \tau(x)$ is a scalar function, $\theta := \theta_i(x)y^i$ is a 1-form on M and $\theta^l := a^{lm}\theta_m$ and $k_1 := \Pi(0), k_2 := \frac{\Pi'(0)}{Q(0)},$ $k_3 := \frac{1}{6Q(0)^2} \left[3Q''(0)\Pi'(0) - 6\Pi'(0)^2 - Q(0)\Pi''(0) \right],$ $Q := \frac{\phi'}{\phi - s\phi'}, \ \Pi := \frac{\phi'^2 + \phi\phi''}{\phi(\phi - s\phi')}.$

Lemma 3.2. Let

 $F^2 = c_1 \alpha^2 + 2c_2 \alpha \beta + c_1 \beta^2$, $(c_1 \neq 0, c_2 \neq 0)$ be a non-Riemannian generalized Randers metric on a manifold M of dimension $n \ge 3$. Then F is locally dually flat on M if and only if α, β and $\phi = \phi(s)$ satisfy

$$s_{l0} = \frac{1}{3} (\beta \theta_l - \theta b_l), \qquad (3)$$

$$G_{\alpha}^{\prime} = \frac{1}{3} \left[2\theta + \tau \beta \right] y^{\prime} + \frac{1}{3} \left(\theta^{\prime} - \tau b^{\prime} \right) \alpha^{2}, \quad (4)$$

$$r_{00} = \frac{2}{3}\theta\beta + \left[\tau + \frac{2}{3}\left(b^{2}\tau - \theta_{l}b^{l}\right)\right]\alpha^{2} + \frac{5}{3}\tau\beta^{2}, \qquad (5)$$

where $\tau = \tau(x)$ is a scalar function and $\theta = \theta_k y^k$ is a 1-form on M.

Proof: For a generalized Randers metric $F^2 = c_1 \alpha^2 + 2c_2 \alpha \beta + c_1 \beta^2$, we have the following

$$\phi = \sqrt{c_1 + 2c_2s + c_1s^2},\tag{6}$$

$$Q = \frac{c_2 + c_1 s}{c_1 + c_2 s},\tag{7}$$

$$Q' = \frac{c_1^2 - c_2^2}{(c_1 + c_2 s)^2},$$

$$Q'' = \frac{-2c_2(c_1^2 - c_2^2)}{(c_1 + c_2 s)^3},$$
(8)

$$\Pi = \frac{c_1}{c_1 + c_2 s},$$

$$\Pi' = -\frac{c_1 c_2}{\left(c_1 + c_2 s\right)^2},$$
(9)

$$\Pi'' = \frac{2c_1 c_2^2}{\left(c_1 + c_2 s\right)^3},$$

$$\Pi''' = -\frac{6c_1 c_2^3}{\left(c_1 + c_2 s\right)^4},$$
(10)

$$k_1 = 1, \ k_2 = -1, \ k_3 = 0.$$
 (11)

Using (6)-(11), we get:

$$s(k_{2}-k_{3}s^{2})(\phi\phi'-s\phi'^{2}-s\phi\phi'') - (\phi'^{2}+\phi\phi'') + k_{1}\phi(\phi-s\phi') = 0$$

Then by Theorem 3.1, we get the proof.

Now, let $\phi = \phi(s)$ be a positive C^{∞} function on $(-b_0, b_0)$. For a number $b \in [0, b_0)$, let $\Phi := -(Q - sQ') \{n\Delta + 1 + sQ\}$ $-(b^2 - s^2)(1 + sQ)Q''$ (12)

where

$$\Delta := 1 + sQ + \left(b^2 - s^2\right)Q'$$
⁽¹³⁾

By considering (7), the relation (12) can be written as follows:

$$\Phi = -(Q - sQ')(n+1)\Delta +(b^{2} - s^{2})\{(Q - sQ')Q' - (1 + sQ)Q''\}.$$
(14)

Remark 3.1. By a direct computation, we can obtain a formula for mean Cartan torsion of an (α, β) -metric as follows

$$I_{i} = -\frac{\Phi(\phi - s\phi')}{2\Delta\phi\alpha^{2}}(\alpha b_{i} - sy_{i}).$$

 $\Phi = 0.$

Clearly, an (α, β) -metric $F = \alpha \phi(s), \ s = \frac{\beta}{\alpha}$ is Riemannian if and only if

In [8], Cheng-Shen study the class of (α, β) -metrics of non-Randers type $\phi \neq \sqrt{1+t_2s^2} + t_3s$ with isotropic S-curvature and obtain the following.

Theorem 3.3. ([8]) Let $F = \alpha \phi(s)$, $s = \frac{\beta}{\alpha}$ be an non-Riemannian (α, β) – metric on a manifold and $b := ||\beta_x||_{\alpha}$. Suppose that $\phi \neq t_1 \sqrt{1 + t_2 s^2} + t_3 s$ for any constant $t_1 > 0$, t_2 and t_3 . Then F is of isotropic S-curvature S = (n+1)cF, if and only if one of the following holds (*i*) β satisfies

$$r_{ij} = c \left\{ b^2 a_{ij} - b_i b_j \right\}, \quad s_j = 0,$$
 (15)

where $\mathcal{E} = \mathcal{E}(x)$ is a scalar function, and c = c(x) satisfies

$$\Phi = -2\left(n+1\right)k \frac{\phi\Delta^2}{b^2 - s^2} \tag{16}$$

where k is a constant. In this case, S = (n+1)cF with $c = k \varepsilon$. (ii) β satisfies

$$r_{ij} = 0, \quad s_j = 0$$
 (17)

In this case S = 0, regardless of choices of a particular ϕ .

Using the Theorem 3.3, we are going to consider locally dually flat generalized Randers metrics with isotropic S-curvature.

Proposition 3.1. Let

 $F^2 = c_1 \alpha^2 + 2c_2 \alpha \beta + c_1 \beta^2$, $(c_1 \neq 0, c_2 \neq 0)$ be a locally dually flat non-Randers on a manifold M of dimension $n \ge 3$. Suppose that F is of isotropic S-curvature, type and non-Riemannian S = (n+1)cF, where c = c(x) is a scalar function on M. Then F is a locally generalized Randers metric projectively flat in adapted coordinate systems with $G^i = 0$.

Proof: Let $G^{i} = G^{i}(x, y)$ and $\overline{G}_{\alpha}^{i} = \overline{G}_{\alpha}^{i}(x, y)$ denote the coefficients of F and α respectively in the same coordinate system. By definition, we have

$$G^{i} = \overline{G}^{i}_{\alpha} + Py^{i} + Q^{i}$$
⁽¹⁸⁾

where

$$P = \alpha^{-1} \Theta \left\{ -2Q \,\alpha s_0 + r_{00} \right\}, \tag{19}$$

$$Q^{i} = \alpha Q s_{0}^{i} + \Psi \{-2Q \alpha s_{0} + r_{00}\} b^{i}, \qquad (20)$$

$$\Theta = \frac{\phi \phi' - s (\phi \phi'' + \phi' \phi')}{2\phi ((\phi - s \phi') + (b^2 - s^2) \phi'')},$$
$$\Psi = \frac{1}{2} \frac{\phi''}{(\phi - s \phi') + (b^2 - s^2) \phi''}.$$

First, we suppose that the case (i) of the Theorem 3.3 holds. It is remarkable that, for a generalized Randers metric $F^2 = c_1 \alpha^2 + 2c_2 \alpha \beta + c_1 \beta^2$, the following relations hold

$$\phi = \sqrt{c_1 + 2c_2s + c_1s^2},$$
$$Q = \frac{c_2 + c_1s}{c_1 + c_2s},$$
$$Q' = \frac{d}{(c_1 + c_2s)^2},$$

$$Q'' = \frac{-2c_2d}{(c_1 + c_2s)^3}.$$

Where $d := c_1^2 - c_2^2$. Thus we have

$$1 + sQ = \frac{\phi^2}{c_1 + c_2 s}$$
(21)

and then

$$\Delta := 1 + sQ + (b^{2} - s^{2})Q'$$

$$= \frac{(c_{1} + c_{2}s)\phi^{2} + d(b^{2} - s^{2})}{(c_{1} + c_{2}s)^{2}}$$
(22)

By (22), it follows that $(c_1 + c_2 s)^2 \Delta$ is a polynomial in s of degree 3. On the other hand, we have

$$\phi \Delta^{2} = \frac{\phi \left[\left(c_{1} + c_{2} s \right) \phi^{2} + d \left(b^{2} - s^{2} \right) \right]^{2}}{\left(c_{1} + c_{2} s \right)^{4}}$$
(23)

Thus if $\Phi = -2(n+1)k \frac{\phi\Delta^2}{b^2 - s^2}$ holds, then by (23) it results that

$$(b^{2} - s^{2})(c_{1} + c_{2}s)^{4} \Phi$$

$$= -2(n+1)k\phi [(c_{1} + c_{2}s)\phi^{2} + d(b^{2} - s^{2})]^{2}.$$
(24)

By (24), it follows that $(b^2 - s^2)(c_1 + c_2 s)^4 \Phi$ is not a polynomial in s (if k = 0, then by considering the Remark 3.1, we get a contradiction). Indeed, if we put

$$\phi\Delta^2 = \frac{\overline{\Delta}}{\left(c_1 + c_2 s\right)^4},$$

where

$$\overline{\Delta} = \sqrt{c_1 s^2 + 2c_2 s + c_1} \left\{ \left(c_1 + c_2 s \right) \phi^2 + d \left(b^2 - s^2 \right) \right\}^2,$$

then $\overline{\Delta}$ is a polynomial in s and b if and only if $\phi = c_1(\alpha + \beta)$, $(c_1 \ge 0)$. But by assumption F is not a Randers-type metric. So $\overline{\Delta}$ is not a

polynomial in s, and then $(b^2 - s^2)(c_1 + c_2 s)^4 \Phi$ is not a polynomial in s.

Now, we consider another formula for Φ :

$$\Phi = -(Q - sQ')(n+1)\Delta +(b^{2} - s^{2})\{(Q - sQ')Q' - (1 + sQ)Q''\}.$$
(25)

We have

$$Q - sQ' = \frac{c_2 \phi^2}{\left(c_1 + c_2 s\right)^2}.$$
 (26)

by (8), (21), (25) and (26), it follows that

$$\Phi = -\frac{(n+1)c_2\phi^2}{(c_1+c_2s)^2}\Delta + (b^2 - s^2) \left[\frac{c_2d\phi^2}{(c_1+c_2s)^4} + \frac{2c_2d\phi^2}{(c_1+c_2s)^4} \right]$$
$$= -\frac{(n+1)c_2\phi^2 \left[(c_1+c_2s)\phi^2 + d(b^2 - s^2) \right]}{(c_1+c_2s)^4}$$
$$+ \left[\frac{3c_2d(b^2 - s^2)\phi^2}{(c_1+c_2s)^4} \right]$$
$$= \frac{(2-n)c_2d(b^2 - s^2)\phi^2 - (n+1)c_2(c_1+c_2s)\phi^4}{(c_1+c_2s)^4} \quad (27)$$

By (27), it results that for the Φ defined by (25), the relation $(b^2 - s^2)(c_1 + c_2 s)^4 \Phi$ is a polynomial in *s* and *b* of degree 7 and 4, respectively. The coefficient of s^7 is $(n+1)c_1^2c_2^2$. Thus, $\Phi = 0$ is impossible because $c_1^2c_2^2 \neq 0$. Thus, we can conclude that (16) does not hold. Therefore, the case (ii) of the Theorem 3.3 holds. In this case, we have

$$r_{00} = 0,$$
 (28)

$$s_j = 0. (29)$$

By (5) and (28), we obtain

$$\left[\tau + \frac{2}{3}\left(b^{2}\tau - b_{m}\theta^{m}\right)\right]\alpha^{2} = \beta\left[-\frac{2}{3}\theta + \frac{5}{3}\beta\tau\right]$$
(30)

Since α^2 is irreducible polynomial of y^i , then (30) reduces to the following

$$\tau + \frac{2}{3} \left(b^2 \tau - b_m \theta^m \right) = 0, \tag{31}$$

$$-\frac{2}{3}\theta + \frac{5}{3}\beta\tau = 0.$$
 (32)

By (3) we have

$$s_0 = -\frac{1}{3} \left(\theta b^2 - \beta b_m \theta^m \right). \tag{33}$$

It follows from (29) that $s_0 = 0$. Then (33) reduces to

$$\theta b^2 - \beta b_m \theta^m = 0 \tag{34}$$

By (32) and (34), we obtain

$$\frac{2}{3}(1-b^{2})\theta = \frac{2}{3}(1-b^{2})\tau\beta + \left\{\tau + \frac{2}{3}(b^{2}-b_{m}\theta^{m})\right\}\beta.$$
 (35)

Then it follows from (31) and (35) that

$$\theta = \tau \beta \tag{36}$$

By (36) we have

$$\tau b^2 - b^j \theta_j = 0. \tag{37}$$

By (31) and (37), it follows that $\tau = 0$, and by considering (36), we get $\theta = 0$. Therefore (3), (4) and (5) reduce to the following

$$s_{ij} = 0, (38)$$

$$G_{\alpha}^{l} = 0, \tag{39}$$

$$r_{00} = 0.$$
 (40)

Since $s_0 = r_{00} = 0$, then (19) and (20) reduce to

$$P = Q^i = 0 \tag{41}$$

By (18), it follows that $G^{i}_{\alpha} = 0$. This completes the proof.

Proof of Theorem 1.1. By the Proposition 3.1, we conclude that F is dually flat and projectively flat in any adapted coordinate system. By Lemma 2.1, we have

$$F_{x^k} = CFF_{y^k}.$$

The spray coefficients $G^{i} = Py^{i}$ are given by $P = \frac{1}{2}CF$. Since $G^{i} = 0$, then P = 0 and thus

C = 0.

It implies that $F_{x^k} = 0$ and then F is a locally Minkowskian metric in the adapted coordinated system. This completes the proof.

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